Project Title: SmartBike: an Automatically Shifting Bicycle with Other Embedded Features
Students: Frank Pernice, Dylan Dreisch
Advisor: Kenneth Short

Project Objectives:
The goal of this project was to modernize the bicycle riding experience for the 21st century. That is, we strived to replace the mechanical shifters on a multi-speed bicycle with a microcontroller-based electronic system which allows for both manual and automatic shifting while eliminating the issue of cross-chaining.

Significant Results:
• Full manual shifting was implemented in a way which prevents cross-chaining: a problem which plagues novice riders and causes premature chain wear. It does this by ensuring proper gear ratios before making the desired shift.
• Full automatic shifting was implemented by monitoring true speed and pedaling cadence. The microcontroller makes an intelligent decision and shifts into a proper gear ratio relative to the current speed and cadence.
• An Android application was developed to monitor system vitals such as speed, cadence, gear ratio, and temperature.

Approach
The design was implemented with an ATmega128, two servos, two digital Hall-effect sensors, a servo controller, a Bluetooth module, and a power system (which itself consisted of a battery, bottle dynamo, and voltage rectification and regulation circuitry). Code was developed to implement both manual and automatic shifting and an Android application was developed to display information to the user.

Ethical Issues/Impact on Society:
The project aims to bring modern technology to the Great Outdoors. The computer age has given birth to a generation of people who spend their entire lives indoors; we wish to change that.

Ethical Issues/Impact on Society:

Stony Brook University
The State University of New York